**ROS drivers:** [**https://github.com/will-andrew/couch\_driver**](https://github.com/will-andrew/couch_driver)

**Firmware for main and power boards:** [**https://github.com/will-andrew/couch\_fw**](https://github.com/will-andrew/couch_fw)

**Power on:**

1. Turn key to on position
2. Press start button on controller to wake up controller
3. Wait about 30 seconds for it to boot
4. Release E-stop
5. Drive (forward/reverse do not work properly. left/right/rotate is best)

**Power off:**

1. Press E-stop
2. Hold right trigger and X, Y, A, B buttons simultaneously to power off NUC
3. Wait 5 seconds
4. Turn key to off position